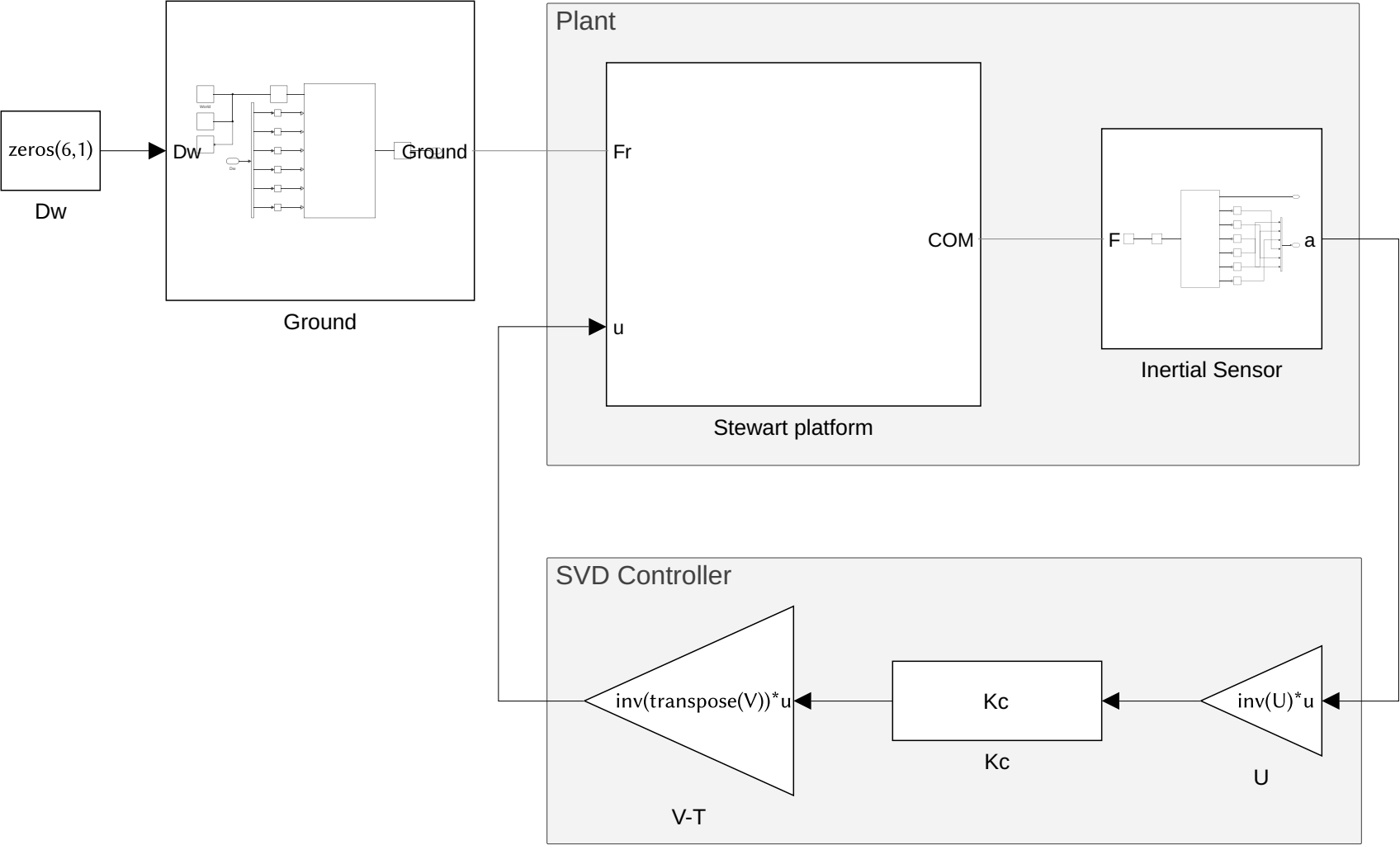
zeros(6,1)
Dw
Dw
Ground
Ground
Plant
Fr
u
COM
Stewart platform
F
a
Inertial Sensor
SVD Controller
inv(transpose(V))*u
V-T
Kc
Kc
inv(U)*u
U