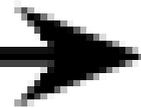


$$\begin{bmatrix} u_{r1} \\ h_1 \\ d_{r1} \end{bmatrix}$$



$$\mathcal{J}_{s,1}^{-1}$$



$$\begin{bmatrix} d_{z1} \\ r_{y1} \\ r_{x1} \end{bmatrix}$$